X.Org Developer’s Conference
2019

Report of Contributions
State of the X.org

Friday, 4 October 2019 14:50 (20 minutes)

Your secretary’s yearly report on the state of the X.org Foundation. Expect updates on the freedesktop.org merger, internship and student programs, XDC, and more!

Code of Conduct
Yes

GSoc, EVoC or Outreachy
No

Presenter: VETTER, Daniel (Intel)
Session Classification: Main Track
FPGAs and their less generic cousin, specialized accelerators have come onto the scene in a way that GPUs did 20 or so years ago. Indeed new interfaces have cropped up to support them in a fashion resembling early GPUs, and some vendors have even opted to try to use DRM/GEM APIs for their devices.

This talk will start with a background of what FPGAs are, how they work, and where they’re currently used. Because the audience is primarily people with graphics/display background, I will make sure to cover this well. It will then discuss the existing software ecosystem around the various usage models with some comparison of the existing tools. If time permits, I will provide a demo comparing open tools vs. closed ones.

The goal of the talk is to find people who have lived through DRI1 days and are able to help contribute their experience (and coding) toward improving the stack for the future accelerators.

Currently, my focus is on helping to improve a fully open source toolchain, and so I will spend more time on that then API utilization.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  WIDAWSKY, Ben

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Contribution ID: 12

Type: not specified

01 (Wednesday): Why does my piglit run take two days?

In this lightening talk, Jason will talk about some of the improvements he's made recently to NIR and the intel back-end compiler to reduce compile times when using software emulated fp64.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: EKSTRAND, Jason (Intel)

Session Classification: Lightning talks

Track Classification: Lightning Talk
Outreachy Internship Report: Refactoring backlight and spi helpers in drm/tinydrm

Wednesday, 2 October 2019 16:10 (20 minutes)

In this talk, I will briefly describe my contributions as an outreachy round 15 intern. Broadly, I worked on refactoring code in the tinydrm subsystem. Specifically, I refactored the backlight and the spi helper functions.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Yes

Presenter: MADHYASTHA, Meghana (Johns Hopkins University)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
Zink: OpenGL on Vulkan

Wednesday, 2 October 2019 08:55 (45 minutes)

Zink is a work-in-progress Mesa Gallium driver that implements OpenGL on top of Vulkan. This talk will discuss why and how, and give an update on what’s happened in Zink recently.

**Code of Conduct**

Yes

**GSoc, EVoC or Outreachy**

No

**Presenter:** FAYE-LUND, Erik (Collabora)

**Session Classification:** Main Track

**Track Classification:** Talk (full slot) (closed)
Abstract

Hardware testing can help catch regressions in driver code. One way to test is to perform manual checks, however this is error-prone and doesn’t scale. Another approach is to build an automatic test suite (e.g. IGT), which calls special driver interfaces or mocks resources to check whether they are doing the right thing (for instance, checksums to check that the right frame is produced).

However it’s not possible to test all features with driver helpers: link training, hot-plug detection, DisplayPort Multi-Stream Transport and Display Screen Compression are examples of hard-to-test features. Moreover, some regressions can be missed because they happen at a lower level than the driver helpers.

For this reason, a board emulating a real screen has been developed: Chamelium. It can be used to test display features from the KMS client to the screen and make sure the whole software and hardware stack works properly. An overview of the Chamelium board features (and limitations) will be presented.

Outline

1. Why:
2. Automated testing is essential to merging patches with confidence
3. It’s not possible to test all display-related features without real hardware
4. Some features can only be tested by adding knobs in the kernel (e.g. by forcing an EDID on a disconnected connector)
5. The tests aren’t checking that the feature works correctly with a real screen
6. How:
7. Google has developed a Chamelium board that emulates a screen
8. Chamelium features
9. Chamelium support in IGT
10. Example of a Chamelium test (quick demo?)
11. Current limitations and possible improvements
12. Features supported by the receiver chips but not exposed by the Chamelium API
13. Features not supported (would require a new board)

Code of Conduct

Yes
GSoC, EVoC or Outreachy

No

Presenter: SER, Simon (sway/wlroots)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
Witchcraft Secrets from a Reverse Engineer

Friday, 4 October 2019 10:45 (45 minutes)

Thousands of moons ago, an obscure magical art developed by the Magic Resistance beneath the disquieting tides of the Magilectric Revolution: reverse-engineering... Some refuse to acknowledge its existence. Some mistakenly believe it a form of witchcraft or dark magic, entranced by its binary spells and shadowy hexes. The outer world rarely catches more than a glimpse of these powerful mages, for each youngling learns from an elder reverse-engineer, under a non-existent disclosure agreement, knowledgeable memcpy'd straight to their brains. A write-only memory spell ensured total secrecy of the art form... until today. Learn the exploits of a young mage and her memory restoration spell. Registers and secrets spilled in this magilectric adventure.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: ROSENZWEIG, Alyssa (Panfrost / Collabora)

Session Classification: Main Track

Track Classification: Talk (full slot) (closed)
How to not write a back-end compiler

Wednesday, 2 October 2019 12:40 (45 minutes)

Compilers are hard and there are always a lot of design decisions involved in trying to come up with the right architecture to target any given piece of hardware. In this talk, Jason will go over some of the design decisions (especially the mistakes) that have been made by the Intel team as well as other established back-ends and how they have worked out in practice. These will be used as motivating examples to discuss current back-end compiler best practices and suggestions for developers working on new back-ends.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  EKSTRAND, Jason (Intel)

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Enabling 8K displays - A story of 33M pixels, 2 CRTCs and no Tears!

Thursday, 3 October 2019 17:35 (20 minutes)

Ever seen a true 33 million pixel 8K display? The maximum display link bandwidth available with DisplayPort’s highest bit rate of 8.1 Gbps/lane limits the resolution to 5K@60 over a single DP connector. Hence the only true 8K displays allowing upto full 60 frames per second are the tiled displays enabled using 2 DP connectors running at their highest bit rate across 2 CRTCs in the display graphics pipeline. Enabling tiled displays across dual CRT dual connector configuration has always resulted in screen tearing artifacts due to synchronization issues between the two tiles and their vertical blanking interrupts.

Transcoder port synchronization is a new feature supported on Intel’s Linux Graphics kernel driver for platforms starting Gen 11 that fixes the tearing issue on tiled displays. In this talk Manasi will explain how port synchronization is plumbed into the existing atomic KMS implementation. She will deep dive into the DRM and i915 code changes required to handle tiled atomic modesets through master and slave CRTCs lockstep mode operation to enable tearfree 8K display output across 2 CRTCs and 2 ports in the graphics pipeline. She will conclude by showing the 8K display results using Intel GPU Tools test suite.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: NAVARE, Manasi (Intel Corporation)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
Nouveau Generic Allocator Implementation in GBM

Thursday, 3 October 2019 14:00 (45 minutes)

I will discuss the results of an effort to implement the concepts discussed in my prior generic Unix device memory allocator talks as extensions to the existing GBM API with a nouveau driver backend. Based on prior feedback, DRM format modifiers will be used in place of what were previously called “capabilities”. I will attempt to demonstrate the feasibility of this less-invasive approach, and demonstrate the performance/efficiency compared to existing GBM usage models.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Presenter:  JONES, James (NVIDIA)
Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
This talk is meant to give an overview on where we stand with KDE’s KWin as an X11 window manager and a Wayland compositor, who is currently working on it and on what tasks now and in the near future.

The topics will broadly be:

- The KWin team
- Technical topics:
  - Abstracting KWin’s internals
  - Updating legacy code / cleaning house
  - Wayland multi device and threaded rendering
  - Learning individually and improving our team coherence
  - KWin as part of the X.Org / freedesktop.org / Wayland community

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

No

**Presenter:** GILG, Roman

**Session Classification:** Main Track

**Track Classification:** Talk (half slot) (closed)
02 (Wednesday): XWayland multi DPI scaling

I want to give a quick overview of my proposed solution for XWayland multi DPI scaling [1].

This is also meant as a query on what other solutions there might be currently in development by other people or even already implemented.

[1] https://gitlab.freedesktop.org/xorg/xserver/merge_requests/111

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: GILG, Roman

Session Classification: Lightning talks

Track Classification: Lightning Talk
A whirlwind tour through the input stack development efforts

Friday, 4 October 2019 09:00 (45 minutes)

The input stack comprises many pieces. libinput, libevdev, libratbag, libwacom and even a few components that don’t start with “lib”. The kernel or X for example, also somewhat of importance.

This talk is a tour of recently added features and features currently in development. Examples include libinput user devices, the difficulty of supporting high-resolution wheel scrolling in Wayland, how we’ve painted ourselves in a corner by using the hwdb in libinput and then tore out the whole room and replaced it with a nicer one, and whacky devices like the totem that will probably never work as they do in the advertising videos. This talk includes blue-sky features full of optimism and may include some features that have no such optimism left and are now merely a pile of discarded branches, soaked with tears.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  HUTTERER, Peter (Red Hat)

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Edging closer to the hardware for kernel CI on input devices

Avoiding regressions in the input stack is hard. Ideally, every commit and the ones before it are tested against every possible device. But the universe hasn’t seen it fit to provide us with an army of people to test devices, infinite resources, or even a lot of time to spare. Pity, that, really. But we do have a computer, so that’s a start.

In this talk we show how we moved from basically no regression tests 10 years ago in the input stack, to a state where every commit gets tested against variety of devices. We show how we can do CI on the kernel side, and how we can do CI on the user space side.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: TISSOIRES, Benjamin (Red Hat)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
GPUs often provide half-float 16-bit registers for floating point calculations. Using these instead of full-precision 32-bit registers can often provide a significant performance benefit, particularly on embedded GPUs. The method used to expose these registers to applications in OpenGLES is that variables can be marked as `mediump`, meaning that the driver is allowed to use a lower precision for any operations involving these variables. The GLES spec allows for the lower precision to be optional so it is always valid to use a higher precision. Mesa currently implements the spec effectively by just ignoring the precision markers and always using full precision.

This talk will present ongoing work at Igalia to implement a lowering pass to convert `mediump` operations to 16-bit float operations. The work is targeting the Freedreno driver but the resulting lowering pass may be applicable to other drivers too.

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

**Presenter:** ROBERTS, Neil (Igalia)

**Session Classification:** Main Track

**Track Classification:** Talk (full slot) (closed)
VKMS Improvements

Earlier setting up the mode (screen resolution, color depth, and refresh rate) for display screen was done through userspace programs, thus exposing system calls and breaking up while changing different modes. In order to configure the mode setting, the dri-devel community developed the Kernel Mode Setting (KMS) code, and API. Virtual Kernel Mode Setting (VKMS) is a newly added device driver in the Linux Kernel that provides virtual KMS implementation for headless systems and DRM test coverage. It will be valuable for running X or Wayland on a headless machine enabling the use of GPU. At the moment that VKMS gets mature enough, it will be used to run i-g-t test cases and to automate userspace testing. In this talk, Shayenne and Mamta will talk about a journey of how they started contributing in Linux Kernel and later ended up debugging and adding features for VKMS driver. They will also explain how VKMS fits in the workflow of a graphics pipeline and also share their experiences as newcomers in the community. Shayenne Moura worked to solve bugs related to vblank issues (VKMS was not synchronized with vblank timestamps) and add i-g-t tests to verify well working, while Mamta contributed to add features like alpha blending and support for overlay planes in this virtual driver. Also, she would like to highlight some more applications of VKMS.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Yes

Primary authors:  MOURA, Shayenne (University of Sao Paulo); SHUKLA, Mamta

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
A case study on frame presentation from user space via KMS

Thursday, 3 October 2019 11:40 (45 minutes)

Traditionally, an application had very little control about when a rendered frame is actually going to be displayed. For games, this uncertainty can cause animation stuttering [0]. A Vulkan prototype extension was added to address this problem [1].

XR (AR/VR) applications similarly need accurate knowledge of presentation timestamps in order to predict the head-pose for the time a frame will be displayed. Here, inaccuracies lead to registration errors (i.e. mismatch between virtual and real head pose), causing users to get motion sickness or to experience swimming of virtual content.

XR compositors also optimize for latency. An already-rendered frame is corrected for the most recent head-pose, right before its scan-out to display. The time between the correction of a frame and its presentation determines the resulting latency. In order to keep this value as low as possible, a compositor needs to control how late a frame can be scheduled in order to make the desired presentation time.

The Atomic KMS API is the lowest-level cross-driver API for programming display controllers on Linux. With KMS, buffers can be submitted directly from user space for display, circumventing traditional presentation layers of graphics APIs (e.g. EGL surfaces or Vulkan swapchains). This way, applications gain exclusive access to the display engine for maximum control. Collabora and DAQRI recently published the kms-quads sample project to demonstrate this technique [2]. While working on this, we identified several issues of the KMS API that make it challenging to implement tightly scheduled buffer presentations as required by the use cases mentioned above. For instance, which part of the scan-out signal timestamps provided by KMS refer to is not well defined. Furthermore, it is unclear what the latest point in time is that a buffer can be submitted to make a specific presentation deadline (see [3] for related discussion). The advent of adaptive-sync support in KMS makes this topic even more complex.

This talk should serve as an introduction and summary to user-driven presentation timing via KMS, based on last year’s experience of implementing a KMS-based AR compositor at DAQRI. We will discuss the use-case, its implementation and demonstrate open problems of this topic, hopefully leading to further discussion at the venue.

[0] https://medium.com/@alen.ladavac/the-elusive-frame-timing-168f899aec92

Code of Conduct

Yes
GSoC, EVoC or Outreachy

No

**Presenter:** FINK, Heinrich (DAQRI)

**Session Classification:** Main Track

**Track Classification:** Talk (full slot) (closed)
Introducing the Vulkan WSI Layer

Wednesday, 2 October 2019 09:50 (20 minutes)

3D graphics with new hardware designs and APIs (such as Vulkan) are evolving rapidly. At the same time, windowing systems evolve with new protocols, use-cases, formats, synchronization mechanisms and so on. To effectively support all this GPU drivers separate the implementation of Windowing System Integration (WSI) from the Core 3D rendering.

In Vulkan, WSI is implemented through windowing-specific surface extensions and a swapchain implementation. However, through the Vulkan layer mechanism, we can naturally decouple the WSI code from the core GPU driver. This can make development simpler by allowing people to focus on either supporting new windowing systems and features or new GPU hardware drivers.

By making use of the Vulkan specification with extensions as an interface between WSI code and rendering drivers, it enables more cross-vendor sharing. This also encourages more standardization in how drivers integrate with the OS and leads to more feature-rich Linux graphics stacks.

Introducing the Vulkan WSI layer: the starting point for a driver-agnostic Vulkan swapchain implementation. We've open sourced a working layer that implements `VK_EXT_headless_surface` and `VK_KHR_swapchain`, as a starting point to develop a generic implementation for the different Linux windowing systems.

We'll present the project and its current status, and open for discussion on how we can best collaborate on this important piece of the wider Linux graphics puzzle.

https://gitlab.freedesktop.org/mesa/vulkan-wsi-layer

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters: ZHELEV, Rosen (ARM); Mr GARBETT, David (ARM); Mr FRANCHIN, Matteo (ARM)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
Lima driver status update

Thursday, 3 October 2019 15:45 (45 minutes)

Lima is an open source graphics driver which supports Mali 400/450 embedded GPUs from ARM via reverse engineering.
Recently, after many years since the beginning of the reverse engineering efforts on these devices, the lima driver has been finally upstreamed in both mesa and linux kernel counterparts.
This talk will cover some information about the target GPUs and implementation details of the driver.
It will also include a history of the work done so far to make it possible and the recent efforts which lead to its inclusion in upstream.
Lima is a project under development and many features are still missing for it to become a complete graphics driver.
The aim of this talk is to discuss about its current state and how it is expected to improve going forward.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters:  NUNES, Erico; KHORUZHICK, Vasily; ABBOTT, Connor (Valve)
Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Improving frame timing accuracy in Mesa, DRM and X

Smooth animation of graphics requires that the presentation timing of each frame be controlled accurately by the application so that the contents can be correctly adjusted for the display time. Controlling the presentation timing involves predicting when rendering of the frame will be complete and using the display API to request that the frame be displayed at a specific time.

Predicting the time it will take to render a frame usually draws upon historical frame rendering times along with application heuristics. Once drawn, the display API is given the job of presenting the content to the user at the specified time. A failure of either of these two mechanisms will result in content being delayed, and a stuttering or judder artifact made visible to the user.

Historical timing information includes both the time taken to render a frame with the GPU along with the actual time each frame was displayed to the user. Ideally, the application will also be given some estimate of how long it will take to ready the frame for display once the presentation request has been delivered to the display system. With these three pieces of information (application GPU time, actual display time, presentation overhead), the application can estimate when its next frame will be ready for display.

The following work is underway to provide applications this information and to improve the accuracy of display presentation timing in the Linux environment.

1. Vulkan GOOGLE_display_timing extension implementation in Mesa. This offers applications some fairly straightforward measurements that can help predict when a frame timing target might be missed.

2. Heuristics in the X Composite and Present extension implementations to improve accuracy of reported display times to Present-using applications

3. Additions to Composite that replace the above heuristics with precise timing information for Compositing managers modified to support these additions.

4. Semi-automatic compositing support added to the Composite extension which allow in-server compositing of some windows to reduce variability in the display process.

This presentation will describe the above work and demonstrate the benefits of the resulting code.

Code of Conduct
Improving frame timing accuracy

Yes

GSoC, EVoC or Outreachy

No

Presenter:  PACKARD, Keith (Valve)

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Bulk moving mechanism on LRU for DRM/TTM

Thursday, 3 October 2019 14:55 (20 minutes)

While investigating a performance issue with the F1 2017 game benchmark, we identified some bottlenecks related to how ttm and amdgpu do buffer validation and LRU handling. This ultimately lead to a major redesign of how we handle buffer migration. This talk describes process that we took to identify and fix the bottleneck and what we learned along the way.

The Talos Principle (Vulkan) Clpeak (OCL) BusSpeedReadback (OCL) /unit: ms
Original 162.1 FPS 42.15 us 0.254 (1K) 0.241 (2K) 0.230 (4K) 0.223 (8K) 0.204 (16K)
Bulk Move 162.4 FPS 44.48 us 0.260 (1K) 0.274 (2K) 0.249 (4K) 0.243 (8K) 0.228 (16K)
Original (move PT bo on LRU) 147.7 FPS 76.86 us 0.319 (1K) 0.314 (2K) 0.308 (4K) 0.307 (8K) 0.310 (16K)
Bulk Move (move PT bo on LRU) 163.5 FPS 40.52 us 0.244 (1K) 0.252 (2K) 0.213 (4K) 0.214 (8K) 0.225 (16K)

<-- With the best performance and highest FPS at the same time

Reference:

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Presenter: HUANG, Ray (AMD GPU driver)

Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
Implementing Optimizations In NIR

Wednesday, 2 October 2019 14:50 (45 minutes)

As more applications come to Linux and drivers move to NIR, the need to perform both application-specific and device-specific shader optimizations increases. Over the past year, numerous enhancements to existing optimizations and new optimization passes have been implemented. Tools and techniques developed from that experience will be presented. The emphasis will be to finding, diagnosing, and validating various kinds peephole optimizations passes and optimizations for NIR’s algebraic optimization pass.

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

No

**Presenter:** ROMANICK, Ian (Intel)

**Session Classification:** Main Track

**Track Classification:** Talk (full slot) (closed)
Monado: Open Source Augmented & Virtual Reality

Thursday, 3 October 2019 09:00 (45 minutes)

VR took off for the consumer with the release of Oculus consumer hardware. But the hardware lacked open source drivers and Linux support in general. The OpenHMD project was created to solve this issue. The consumer VR space has now grown from a kickstarter campaign into a large industry. But this growth has its down sides, multiple companies have their own APIs competing. Luckily these companies have agreed to work on a single API under the Khronos umbrella. Now that provisional spec of OpenXR has been released, the Monado project has been launched, a follow up to OpenHMD.

In this talk, Jakob will cover Monado and Khronos’ OpenXR standard, give an overview about the current state of open source VR and what lies ahead.

Jakob works for Collabora with graphics and virtual reality, XR Lead at Collabora and a member of the OpenXR working group. He has worked with Linux graphics since 2006, starting with Tungsten Graphics and moving into VMware. In 2013 he along with a friend started the OpenHMD project, then in the spring of 2019 was involved in launching both Monado and OpenXR at GDC.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters: HAAG, Christoph; FERWERDA, Joey (Collabora / OpenHMD)

Session Classification: Main Track

Track Classification: Talk (full slot) (closed)
Freesync, Adaptive Sync & VRR

Thursday, 3 October 2019 16:40 (45 minutes)

DP adaptive sync, a feature supported by AMD under the marketing name of Freesync, primarily allows for smoother gameplay but also enables other use cases, like idle desktop powersaving and 24Hz video playback. In this talk we'll describe what adaptive sync is, how it works, and will speak to different use cases and how they might be implemented. The presentation will cover design and code snippets to show how the feature is enabled.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Co-authors: KAZLAUSKAS, Nicholas (AMD); KOO, Anthony (AMD)

Presenter: WENTLAND, Harry (AMD)

Session Classification: Main Track

Track Classification: Talk (full slot) (closed)
Linux Graphics CI: Standardizing the kernel CI workflow and hardware, and improving our testsuites

Wednesday, 2 October 2019 15:45 (20 minutes)

There are many Linux kernel-testing projects, most of them are modeled over proven software testing workflows. These workflows however often rely on a stable host platform and stable test results and, as such, don’t apply to testing development versions of Linux where the filesystem, network, boot, or suspend might be unreliable.

The Intel GFX CI debuted in 2016 with a different workflow: providing pre-merge curated testing results in a timely manner to all patch series posted on the intel-gfx mailing list. The IGT tests would get executed on Intel platforms spanning from 2004 to upcoming platforms. Known issues are automatically associated to bugs to focus the report on what the developer is trying to change, making it easier to review the change.

After years of experimenting and refining this workflow, the GFX CI team became confident that it was generic-enough and went on to standardize interfaces between the different components in order to enable other drivers to reproduce the testing workflow and collaborate on the development of IGT and related tools.

An example of related tools comes from Google’s ChromeOS validation HW (Chamelium) which acts as an open hardware re-programmable screen with DP, HDMI, and VGA inputs. After initial work from Red Hat in IGT to support the Chamelium, Intel took on the project and have achieved a level of testing for Display Port and HDMI comparable to their official conformance test suites. This massively increases the level of testing achievable in an automated testing system, and not just for Intel, but for GPUs support DP and/or HDMI.

Finally, a new test suite for the KMS interface is being designed around VKMS in order to test how Xorg and Wayland compositors behave in the presence of GPU (un)hotplugging, bandwidth limitations for planes, DP link status issues, etc… This should further improve the reliability of the userspace when it comes to hard-to-reproduce events, regardless of the GPU driver being used!

In this talk, I will compare the different linux testing projects, introduce the i915 CI workflow and tools, the open sourcing and standardization effort going on in i915-infra, the recent development in IGT/Chamelium, and the plan to test Wayland compositors. Let’s work together on standardizing our testing, and moving to a model where not only the i915 driver, but all the drivers would be validated before every commit!

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter: PERES, Martin

May 7, 2021
Session Classification: Main Track

Track Classification: Talk (half slot) (closed)
006 (Friday): IGT GPU Tools Update

Short update on IGT - what has changed, where are we currently and what is cooking up.

IGT GPU Tools is a collection of tools and tests aiding development of DRM drivers. It's widely used by Intel in a public CI system, has targeted tests for v3d, panfrost, amdgpu, etc., and helped to test-drive development of VKMS.

I am one of the maintainers.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  Mr HILER, Arkadiusz

Session Classification:  Lightning talks

Track Classification:  Lightning Talk
DRM/KMS for Android

Friday, 4 October 2019 14:00 (20 minutes)

Update on DRM/KMS driver validation for the Android Open Source Project (AOSP).

- Status update on adding IGT to AOSP, Android VTS.
- Pixel DRM/KMS status update.
- Generic Kernel Image (GKI)

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  DELVA, Alistair (Google)

Session Classification:  Main Track

Track Classification:  Talk (half slot) (closed)
ACO, a new compiler backend for GCN GPUs

Radv (the radeon vulkan driver) has for a long time used LLVM as the shader compiler backend. However, LLVM has a number of issues which led us to develop an alternative shader compiler that strongly leans on the shared nir intermediate language. This new compiler is showing significant gains for compile time as well as runtime performance.

We will talk about our pain points with LLVM and how ACO solves them, the overall design of ACO as well as the challenges we see and the plans we have for the future.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters:  NIEUWENHUIZEN, Bas (Google); SCHÜRMANN, Daniel (Valve)

Session Classification:  Main Track

Track Classification:  Talk (full slot) (closed)
Opening Session

Wednesday, 2 October 2019 08:30 (20 minutes)

Presenter: FILION, Mark (Collabora)

Session Classification: Main Track
Opening Session

Thursday, 3 October 2019 08:45 (10 minutes)

**Presenter:** FILION, Mark (Collabora)

**Session Classification:** Main Track
The Khronos Group industry consortium has created and evolved many key graphics open standards such as OpenGL and Vulkan – and strongly supports their use in open source platforms. Come and hear about the latest Khronos initiatives and roadmap updates, and participate in an AMA session with Neil Trevett, Khronos President.

Code of Conduct

GSoC, EVoC or Outreachy

**Presenter:**  TREVETT, Neil (Khronos Group)

**Session Classification:**  Main Track

**Track Classification:**  Talk (half slot) (closed)
X.Org Foundation Board of Directors Meeting

Thursday, 3 October 2019 18:00 (1 hour)

Session Classification: Main Track

Track Classification: Talk (full slot) (closed)
Opening Session

Friday, 4 October 2019 08:45 (10 minutes)

Code of Conduct

GSoC, EVoC or Outreachy

Presenter: FILION, Mark (Collabora)
Session Classification: Main Track
Contribution ID: 67

Type: not specified

Lightning talks

Session Classification: Main Track

Track Classification: Lightning Talk
Closing session

Friday, 4 October 2019 17:25 (20 minutes)

Code of Conduct

GSoC, EVoC or Outreachy

**Presenter:**  STONE, Daniel (Collabora)
**Session Classification:**  Main Track
Contribution ID: 69

03 (Wednesday): Update on OpenChrome Project

I will discuss the latest development in OpenChrome Project, including the progress being made on OpenChrome DRM.

Code of Conduct

Yes

GSoc, EVoC or Outreachy

Presenter: BRACE, Kevin (Brace Computer Laboratory)

Session Classification: Lightning talks

Track Classification: Lightning Talk
007 (Friday): Reviving vintage (underserved) graphics hardware on X Server

I will discuss my effort to maintain, bug fix, and further develop vintage (underserved) graphics hardware device drivers. I will go over the accomplishments in this area so far, future plans, and challenges of working with older generation hardware in today’s world.

Code of Conduct
Yes

GSoC, EVoC or Outreachy
No

Presenter:  BRACE, Kevin (Brace Computer Laboratory)
Session Classification:  Lightning talks
Track Classification:  Lightning Talk
**04 (Wednesday): Moving the Linux Desktop to another Reality**

AR and VR did not only introduce a new class of output devices, but with tracked controllers and hands also the requirement for a new set of user interactions. This talk investigates solutions in existing implementations and points out how the classical UX model with keyboard and mouse translates to these new devices. The technical aspect of these requirements will also be highlighted. The audience will get an overview of the status of Open Source in XR and the opportunities for Linux desktops.

We present an implementation that integrates VR in the Linux desktop, featuring 3D window management and desktop input synthesis. Initial integrations for Gnome and KDE will be presented.

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

No

**Presenter:** HAAG, Christoph (Collabora)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk
008 (Friday): Panfrost status update

This lightning talk will provide a status update on the open-source graphics stack for Mali Midgard GPUs, including a demo of new features developed since XDC2018.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters: ROSENZWEIG, Alyssa (Panfrost / Collabora); VIZOSO, Tomeu (Collabora)

Session Classification: Lightning talks

Track Classification: Lightning Talk
009 (Friday): gitlab CI for Mesa

I’d like to give a lightning talk about the Mesa gitlab CI system I’ve been building for freedreno and the swrast drivers, and how other driver teams could extend it to keep master always green for them, too.

Code of Conduct
Yes

GSoC, EVoC or Outreachy

Presenter: ANHOLT, Eric (Google)
Session Classification: Lightning talks
Track Classification: Lightning Talk
0091 (Friday): LunarG Mesa Regression Testing

Quick demo of the Mesa regression testing being done by LunarG on Mesa releases.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Presenter:  Ms GHAVAM, Karen (LunarG, Inc)

Session Classification:  Lightning talks

Track Classification:  Lightning Talk
Cameras and Displays: how much can we share?

Friday, 4 October 2019 09:00 (1h 30m)

There are similarities between Camera and Display. On how they work and how we interact with them. For example, both need an Atomic API, share the same buffer formats and need features like explicit fences. On the other hand cameras are much more complex devices where many cameras have very special and unique needs. We want to improve the camera support in Linux and their interoperability with the rest of the kernel benefiting as much as we can from the existing code base and knowledge built by the community.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenters:  PADOVAN, Gustavo (Collabora); PINCHART, Laurent (Ideas on Board)

Session Classification:  Workshop

Track Classification:  Workshop Discussion Topic
0092 (Friday): SwiftShader - a Vulkan Reference Implementation

SwiftShader is a CPU-based implementation of the Vulkan graphics API. It enables consistent testing of Vulkan applications without a dependency on specific hardware, or provides fallback support for running applications on systems without a Vulkan-capable GPU or driver.

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

No

**Presenter:** CAPENS, Nicolas (Google)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk
Mesa CI: Next Steps

Thursday, 3 October 2019 15:45 (2 hours)

Since XDC 2018, substantial progress has been made towards automated testing of Mesa. Lots remains to be done and in this session we will be able to discuss existing proposals and problems.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

Presenters: VIZOSO, Tomeu (Collabora); PERES, Martin

Session Classification: Workshop

Track Classification: Workshop Discussion Topic
Let’s make KMS planes useful for compositors

Wednesday, 2 October 2019 12:40 (2 hours)

Some DRM drivers have been exposing overlay planes for quite some time. Overlay planes can improve battery consumption by scanning out directly client buffers, skipping composition. While compositors usually take advantage of the cursor plane (and sometimes are able to use the primary plane to scan out directly a client’s buffer), overlay planes are under-used.

The exception is Weston, which tries to use overlay planes (more work is underway, see https://gitlab.freedesktop.org/wayland/weston/issues/275). Other compositors ignore overlay planes.

The main challenge is to figure out how to assign buffers coming from clients to hardware planes. The only API exposed by KMS is atomic test commits, so user-space needs to try different combinations.

It would be nice to have a common library shared between compositors to de-duplicate the work. The library I have in mind offers an API similar to Android’s hwcomposer: you give it a scenegraph, it figures out how to allocate planes.

I’ve started an experiment to figure out whether such a library would be viable: https://github.com/emersion/libliftoff

Getting feedback from compositor writers and DRM experts would be useful to push the project forward. Come and help making planes useful for compositors!

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Primary author: SER, Simon (sway/wlroots)

Session Classification: Workshop

Track Classification: Workshop Discussion Topic
XDC 2019 Reception @ Bier Markt

Wednesday, 2 October 2019 19:30 (3 hours)

After a busy first day of presentations, we’ve reserved a space for all attendees at Bier Markt on René-Lévesque Boulevard West, and the first round of drinks, whether alcoholic or non-alcoholic, will be sponsored by X.Org! With one of the best beer lists in Montreal (150 from over 30 countries and over 40 local crafts), and some great food, it will be the perfect place to unwind and network with fellow attendees!

0093 (Friday): RAPID: Realtime Approximate Ink Display

A quick introduction to a compositor-driven approach to input latency reduction. Discuss the idea of introducing an “inking” protocol that uses compositor tricks to cover over application and network latency.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  GERECKE, Jason (Wacom)
Session Classification:  Lightning talks
Track Classification:  Lightning Talk
0094 (Friday): xserver maintenance plans

Hey, the X server still exists. Right now nobody is planning any releases, but things still get merged and should get released. This talk will present a strawman proposal for automated major releases and policy for stable releases.

Code of Conduct

Yes

GSoC, EVoC or Outreachy

No

Presenter:  JACKSON, Adam (Red Hat, Inc.)
Session Classification:  Lightning talks
Track Classification:  Lightning Talk
Contribution ID: 84

mediump breakout session

Thursday, 3 October 2019 09:55 (2 hours)

breakout session to continue mediump discussion

Code of Conduct
Yes

GSoC, EVoC or Outreachy

Primary authors:  CLARK, Rob (Google); ROBERTS, Neil (Igalia)
Session Classification:  Workshop
Track Classification:  Workshop Discussion Topic
Contribution ID: 85

**001 (Friday): Workshop summary - Let’s make KMS planes useful for compositors**

Lightning talk summarizing the discussions that happened during the workshop “Let’s make KMS planes useful for compositors” (https://xdc2019.x.org/event/5/contributions/583/).

**Code of Conduct**

Yes

**GSoC, EVoC or Outreachy**

No

**Presenter:** SER, Simon (sway/wlroots)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk
Allocator discussion

Friday, 4 October 2019 10:30 (1h 30m)

Presenter: JONES, James (NVIDIA)
Session Classification: Workshop
Track Classification: Workshop Discussion Topic
002 (Friday): Workshop summary - Medium breakou session

Code of Conduct

GSoC, EVoC or Outreachy

Presenters: ROBERTS, Neil (Igalia); CLARK, Rob (Google)

Session Classification: Lightning talks

Track Classification: Lightning Talk
003 (Friday): Workshop summary - Mesa CI: next steps

Code of Conduct

GSoC, EVoC or Outreachy

Presenter: PERES, Martin
Session Classification: Lightning talks
Track Classification: Lightning Talk
Contribution ID: 89

**004 (Friday): Workshop summary - Cameras and Displays: how much can we share**

**Code of Conduct**

**GSoC, EVoC or Outreachy**

**Presenter:** PINCHART, Laurent (Ideas on Board Oy)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk
005 (Friday): Workshop summary - Allocator discussion

Code of Conduct

GSoC, EVoC or Outreachy

**Presenter:** RITGER, Andy (NVIDIA)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk
0095 (Friday): Easy project naming

**Code of Conduct**

**GSoc, EVoC or Outreachy**

**Presenter:** HUTTERER, Peter (Red Hat)

**Session Classification:** Lightning talks

**Track Classification:** Lightning Talk